



QUICK START GUIDE

VAB-820

Android EVK v5.0.6



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## Revision History

Version	Date	Remarks
1.00	08/08/2017	Initial release
1.01	08/11/2017	Updated section 1.1 heading name

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# 1. Introduction

This Quick Start Guide provides an overview on how to boot the Android EVK system image for the VAB-820 board and configure the supported hardware functions in the build.

The VAB-820 Android EVK v5.0.6 is developed based on the NXP android\_m6.0.1\_1.0.0-ga (Android 6.0 Marshmallow) and it enables the hardware features of the VAB-820 board.

## 1.1. EVK Package Contents

There are three folders in the package as listed below.

Firmware folder	Description
Images_autoinstall_sd.zip	Android EVK system image and installation script files
Document folder	Description
VAB-820_Android_EVK_v5.0.6_Quick_Start_Guide_v1.01_20170811.pdf	Quick Start Guide
Tools folder	Description
VAB-820_Smart_ETK_Demo_v1.0.apk	Smart ETK demo program
BluetoothSPPTest.apk	Bluetooth SPP testing program

VAB-820 Android EVK contents

### 1.1.1. Firmware Folder Contents

**Images\_autoinstall\_sd.zip:** contains installation script files and the precompiled U-boot and Android image for evaluating the VAB-820 board.

### 1.1.2. Document Folder Contents

**VAB-820\_Android\_EVK\_v5.0.6\_Quick\_Start\_Guide\_v1.01\_20170811.pdf:** This Quick Start Guide provides an overview on how to boot the Android EVK system image on the VAB-820 board and configure the supported hardware functions in the build.

### 1.1.3. Tools Folder Contents

**VAB-820\_Smart\_ETK\_Demo\_v1.0.apk:** is the Smart ETK demo program.

**BluetoothSPPTest.apk:** is the Bluetooth SPP profile test program.

## 1.2. Version Information and Supported Features

- U-Boot version: 2015.04
- Kernel version: 3.14.52
- Evaluation image: Android Marshmallow 6.0
- Development based on NXP android\_M6.0.1\_1.0.0-ga (Android 6.0 Marshmallow)
- Supports SPI with eMMC boot
- Supports HDMI display
- Supports AUO LVDS capacitive touch panels (through USB interface)
  - AUO 10.4 G104XVN01.0 (1024×768)
  - AUO 7 G070VW01 (800×480)
- Supports HDMI audio output
- Supports Dual Display (Clone Mode)
- Supports CVBS & S-Video
- Supports COM1 DTE mode, COM2 TX/RX only
- Supports 2 FlexCAN TX/RX
- Supports Gigabit Ethernet
- Supports Line-in, Line-out, and Mic-in
- Supports VNT9271 USB Wi-Fi dongle
- Supports EMIO-1533 USB Wi-Fi module
- Supports EMIO-1541 miniPCle Wi-Fi module
- Supports EMIO-2531 miniPCle Wi-Fi & Bluetooth module
  - Supports Bluetooth A2DP and SPP profile
- Supports EMIO-2550 miniPCle Mobile Broadband module
- Supports EMIO-5531 USB Wi-Fi & Bluetooth module
  - Supports Bluetooth A2DP and SPP profile
- Supports Smart ETK v1.0: Watchdog Timer, GPIO, UART, and FlexCAN
- Supports OTA (Over-The-Air technology)
- Supports shutdown option in Quick Settings
- Supports Ethernet configuration in Settings

## 2. Image Installation

The VAB-820 only supports booting Android from the SPI ROM and eMMC. This section explains the setup requirements for booting from the SPI ROM and eMMC.

The installation script files, the precompiled U-boot and image are provided in the "Firmware" folder.

### 2.1. Booting from the SPI ROM with eMMC

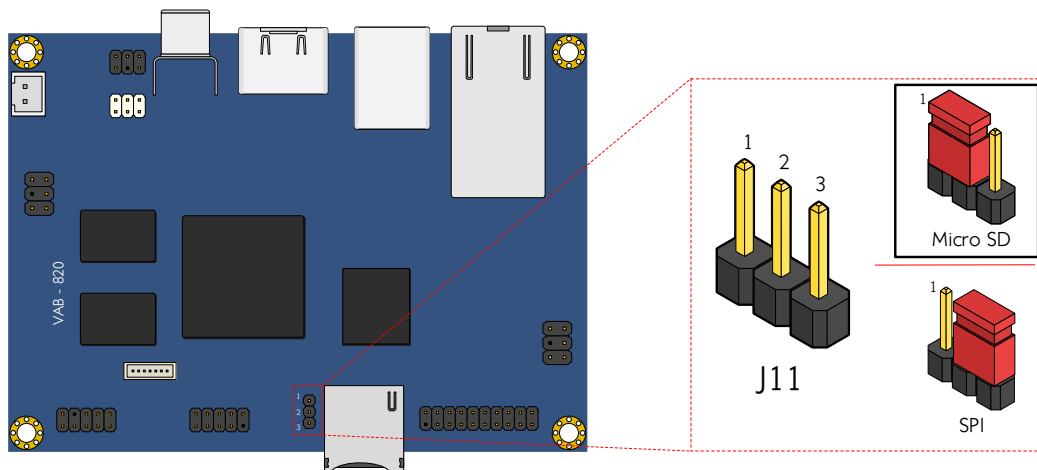
The **Images\_autoinstall\_sd.zip** includes two versions of the Android EVK system image (NXP i.MX6 Quad and i.MX6 Quad Plus) and the installation scripts files.

The first step is to extract the **Images\_autoinstall\_sd.zip** file to make a bootable Micro SD card. Insert a Micro SD card into your Linux host machine and make sure it is not mounted. Open the terminal on your host machine. Select into the iMX6Q or iMX6QP folder to run the **mk\_android6\_inst all\_sd.sh** as shown below, replacing <device name> with the correct value for the card, for example "sdb".

Important: Make sure you are writing to the correct device or the host system environment could be damaged.

```
$ sudo ./mk_android6_install_sd.sh /dev/<device name>
```

Next, on the VAB-820, set the boot select jumper (J11) to the Micro SD position as shown below.



Micro SD / SPI boot select jumper diagram

Insert the prepared Micro SD card into the VAB-820, connect an HDMI display, and power on the VAB-820 to initiate the update process automatically.

```

VIA Technologies, Inc.
iMX6_Android6.0.1_v5.0.2_beta1
-----

U-Boot Version : v2015.04-0.1.0
Kernel Version : v3.14.52-0.1.0

Base File System Version : 0.1.0
Reference File System Version : 0.1.0
OtherInfo :

[Progress Bar] 30 %
erasing spi flash (mtd0)

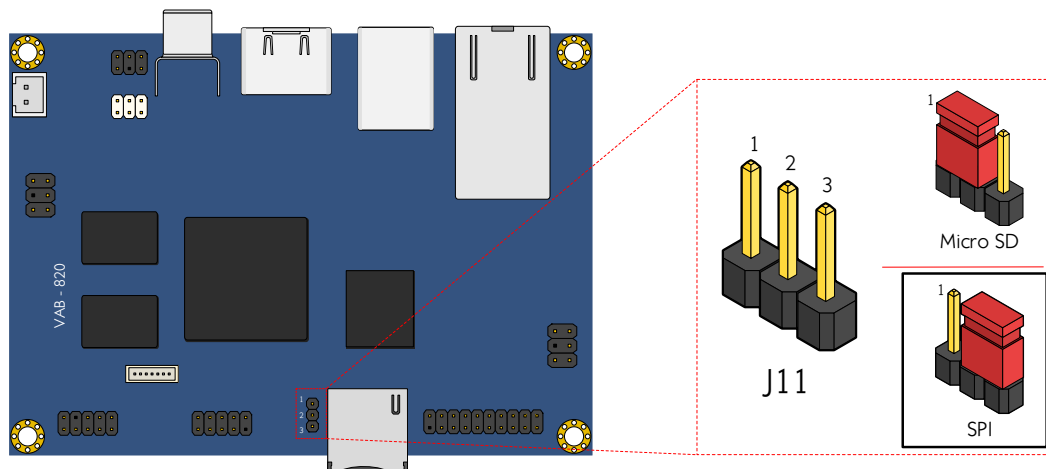
Warnings! Please don't power off! Please wait...

```

Update process screen

When the install process is completed, unplug the power cable and remove the Micro SD card.

In order to boot from the SPI ROM make sure the Micro SD/SPI boot switch is set to SPI ROM boot.



Micro SD / SPI boot select jumper diagram

Next, power on the device to initiate the boot process. When the boot process is completed, you will see the Android desktop.



## 3. Hardware Functions

This section explains how to enable and test the hardware functions precompiled in the Android EVK including setting u-boot parameters, restoring default u-boot parameters, using the Android console, setting up display device, setting up the video-in as well as installing and applying the different functions included in the VIA Smart ETK sample program.

### 3.1. Setting Up U-Boot Parameters

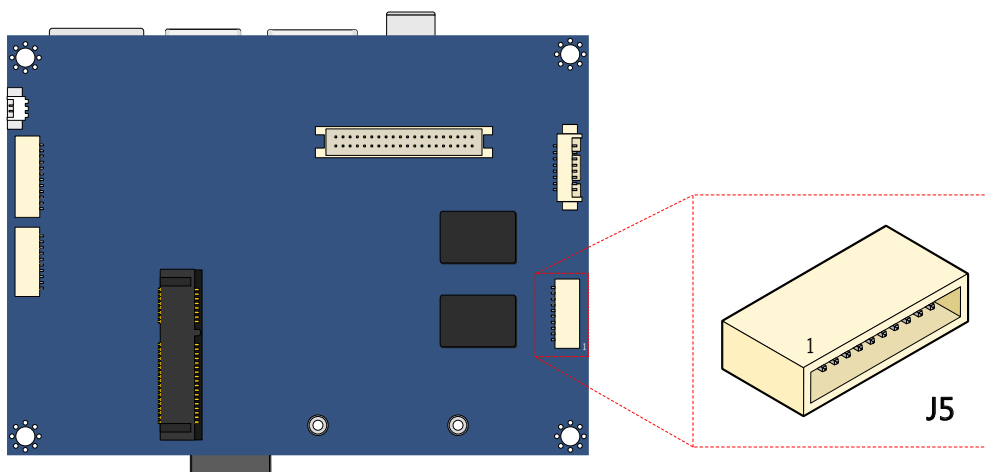
The first step is to connect the host machine and the VAB-820 through the COM 2 connector (J5). Use a serial port communication program such as PuTTY, GtTerm, or Minicom, to configure the serial port setting and connect to the debug console. There you will be able to see the U-Boot boot log and adjust settings in the U-Boot console.

```

+-----+
| A -      Serial Device           : /dev/ttymx0 |
| B -      Lockfile Location       : /var/lock  |
| C -      Callin Program          :           |
| D -      Callout Program         :           |
| E -      Bps/Par/Bits            : 115200 8N1 |
| F -      Hardware Flow Control   : No        |
| G -      Software Flow Control   : No        |
+-----+

```

Serial port setting of host machine



COM 2 connector (J5) diagram

Next, power on the VAB-820 to initiate the boot process. When prompted, press any key to stop the boot process, and enter the U-Boot console as illustrated by the screenshot below.

```
U-Boot 2015.04 (Mar 7 2017 - 18:49:13)VAB820 ver:5.0.4

CPU:   Freescale i.MX6Q rev1.2 at 996 MHz
CPU:   Temperature 30 C, calibration data: 0x5894f169
Reset cause: POR
Board: iMX6Q-VAB820
I2C:   ready
DRAM:  1 GiB
MMC:   FSL_SDHC: 0, FSL_SDHC: 1
SF: Detected W25Q32BV with page size 256 Bytes, erase size 4 KiB,
total 4 MiB
*** Warning - bad CRC, using default environment

No panel detected: default to Hannstar-XGA
Display: Hannstar-XGA (1024x768)
In:     serial
Out:    serial
Err:    serial
Net:    FEC [PRIME]
Warning: failed to set MAC address

Normal Boot
Hit any key to stop autoboot:  0
=>
```

#### Debug console view of boot process

To list the current U-Boot parameters, use the following command:

```
=> printenv
```

Make sure the printout message is as follows:

```
=> printenv

baudrate=115200
boot_emmc_root=mmc dev ${root_media_uboot};ext2load mmc
${root_media_uboot}:${root_partition} ${loadaddr} uImage;ext2load  mmc
${root_media_uboot}:${root_partition} ${dtbaddr} imx6q-vab820.dtb;bootm ${loadaddr} -
${dtbaddr};
boot_media=booti mmc1
```

## 3.2. Restoring Default U-Boot Parameters

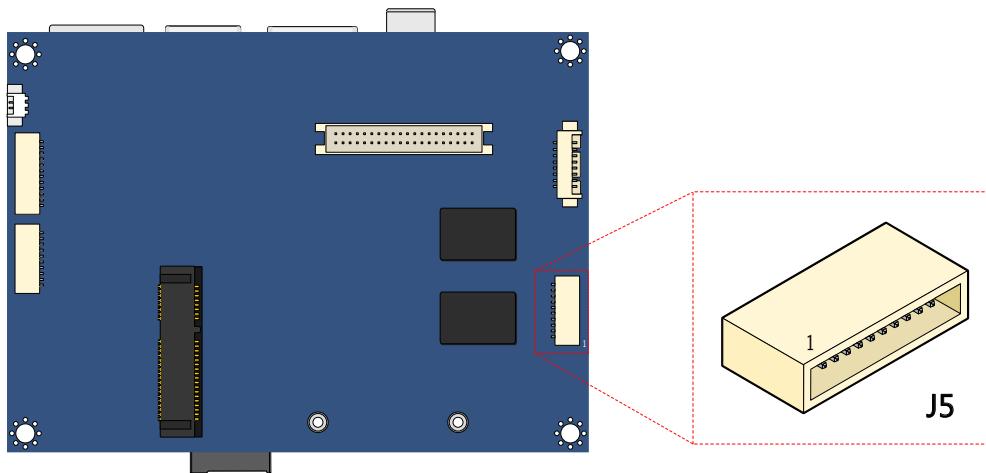
If the U-Boot parameters have been modified, the “destroyenv” command in the U-Boot console can restore the factory default settings.

To restart the device, use the reset command.

```
=> destroyenv
=> saveenv
=> reset
```

## 3.3. Using the Android Console

The first step is to connect the host machine and the VAB-820 through the COM 2 connector (J5). Use a serial port communication program such as PuTTY, GtTerm, or Minicom, to connect to the debug console.



COM 2 connector (J5) diagram

Next, power on the VAB-820 to initiate the boot process. When the boot process is completed, you will automatically log in to the Android console.

```
root@vab820_6dq:/ #
```

## 3.4. Configuring Display Parameters

The VAB-820 Android EVK v5.0.6 supports the following display devices:

- HDMI monitor (default)
- AUO 10.4" G104XVN01.0 LVDS panel (1024x768)
- AUO 7" G070VW01 V0 LVDS panel (800x480)

### 3.4.1. Setting Up the HDMI U-Boot display parameter

To set HDMI as the display output, use the following command:

```
=> setenv display 'run hdm1'
=> saveenv
```

HDMI only supports CEA modes as shown in the table below.

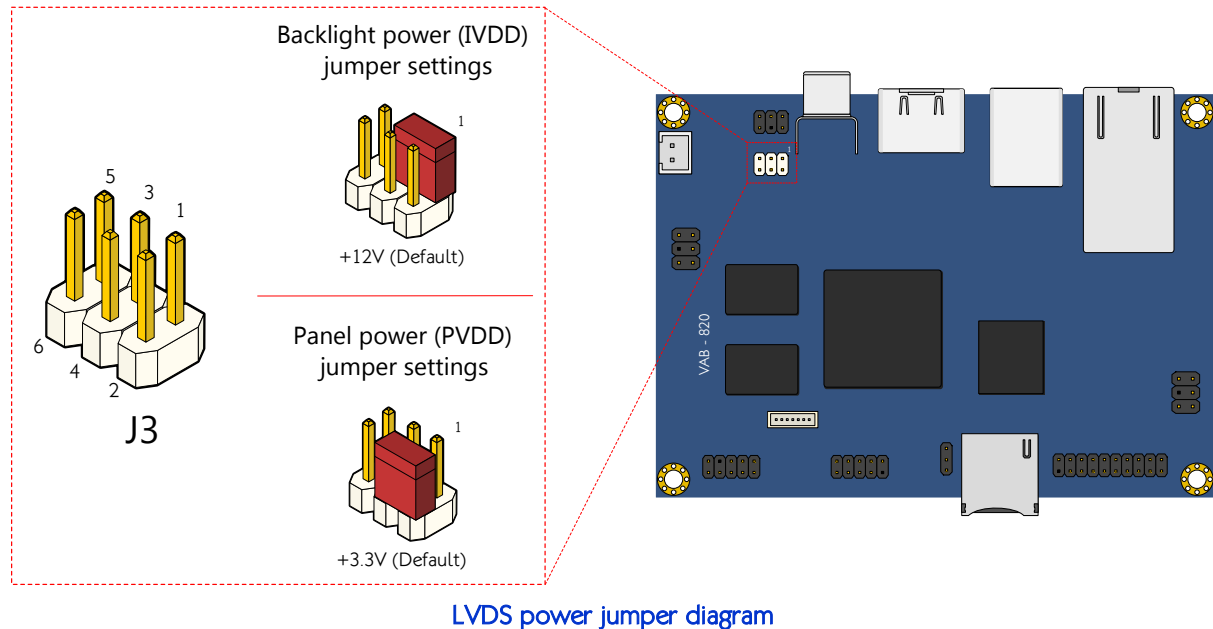
Width	Height	Frame rate
640	480	60
720	480	60
1280	720	60
1440	240	60
1440	480	60
1920	1080	60
720	576	50
1280	720	50
1440	288	50
1440	576	50
1920	1080	50
1920	1080	24
1920	1080	25
1920	1080	30
1280	720	100
1280	720	120

For example, if you would like to set the HDMI resolution to 1280x720@60Hz, use the following command:

```
=> setenv hdm1_timing '1280x720M@60,bpp=32'
=> saveenv
```

### 3.4.3. Setting Up the LVDS U-Boot Display Parameter

Before setting an LVDS panel as the display output make sure the LVDS backlight power select jumper is set to +12V and the LVDS panel power select jumper is set to +3.3V as shown below.



To set the AUO 10.4" G104XVN01.0 LVDS panel as the display output, use the following command:

```
=> setenv display 'run lvds_auo_g104'
=> saveenv
```

In order to confirm the settings are correct use the following command to list the new U-Boot parameters:

```
=> printenv lvds_auo_g104
lvds_auo_g104=video=mxcfb0:dev=ldb,LDB-XGA, if=RGB24 ldb=sin0
```

To set the AUO 7" G070VW01 V0 LVDS panel as the display output, use the following command:

```
=> setenv display 'run lvds_auo_g007'
=> saveenv
```

In order to confirm the settings are correct use the following command to list the new U-Boot parameters:

```
=> printenv lvds_auo_g070
lvds_auo_g070=video=mxcfb0:dev=ldb,480C60,if=RGB24 ldb=sep0
```

### 3.4.4. Setting Up the Dual Display U-Boot Display Parameter

The VAB-820 supports clone mode with an HDMI monitor and LVDS panel. Clone mode will allow the same content to be shown on both display devices.

To set an HDMI monitor and the AUO 10.4" G104XVN01.0 (1024x768) LVDS panel, use the following command:

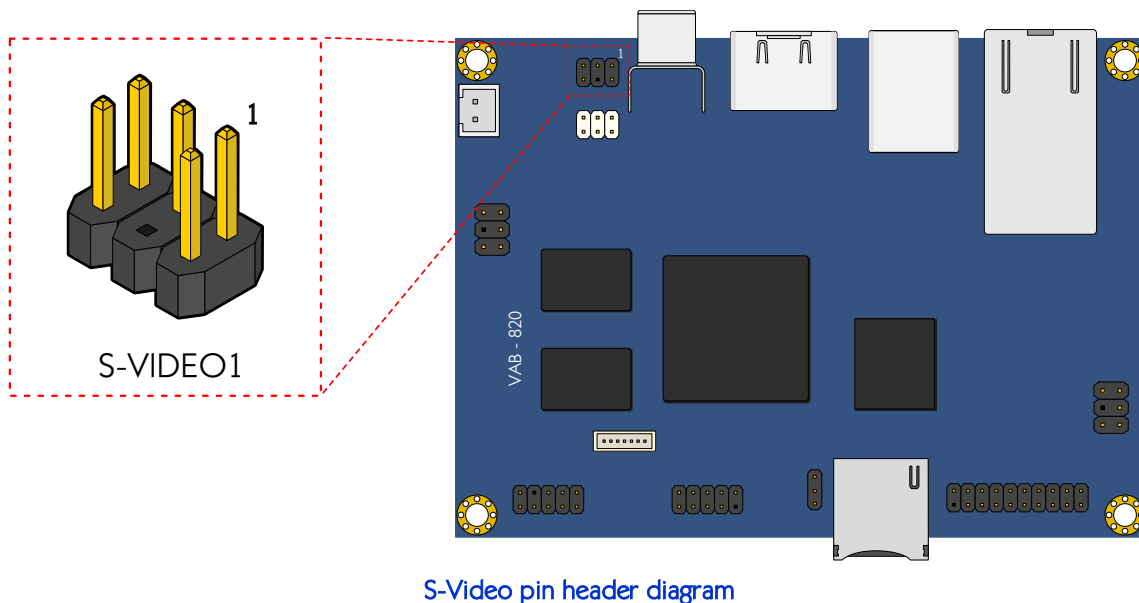
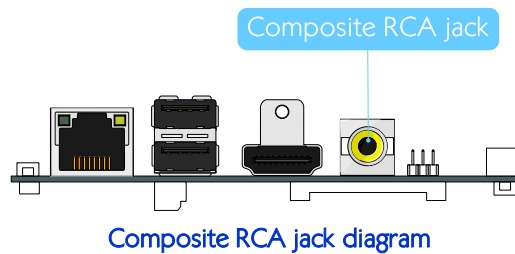
```
=> setenv display 'run hdmi_lvds_g104'  
=> saveenv  
=> reset
```

To set an HDMI monitor and the AUO 7" G070VW01 V0 (800x480) LVDS panel, use the following command:

```
=> setenv display 'run hdmi_lvds_g007'  
=> saveenv  
=> reset
```

### 3.5. Setting Up Video-in

The VAB-820 supports two video inputs. The composite RCA jack is a CVBS signal input and the S-VIDEO1 pin header is an S-Video signal input. The following steps are for video-in function verification.



The CVBS is the default video input.

To set CVBS as video input source, use following the command:

```
root@vab820_6dq:/ # setprop adv7180_src 1
```

To set S-Video as video input source, use following the command:

```
root@vab820_6dq:/ # setprop adv7180_src 2
```

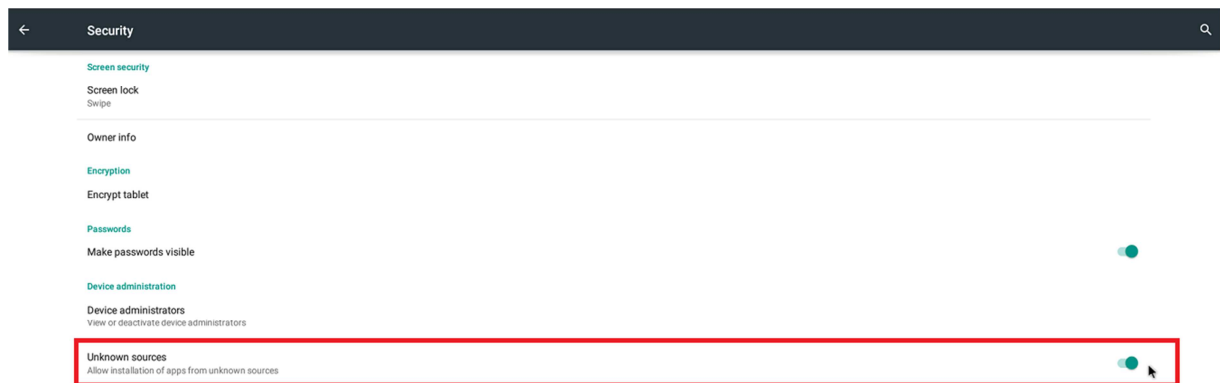
Please note that after the setup is complete, you will need to re-open your Camera program for the settings to be applied.

## 3.6. Smart ETK

The VAB-820 Smart ETK supports Watchdog, GPIO, UART and CAN bus functions. Please follow the procedures below to experiment with the Smart ETK functions on the VAB-820 board.

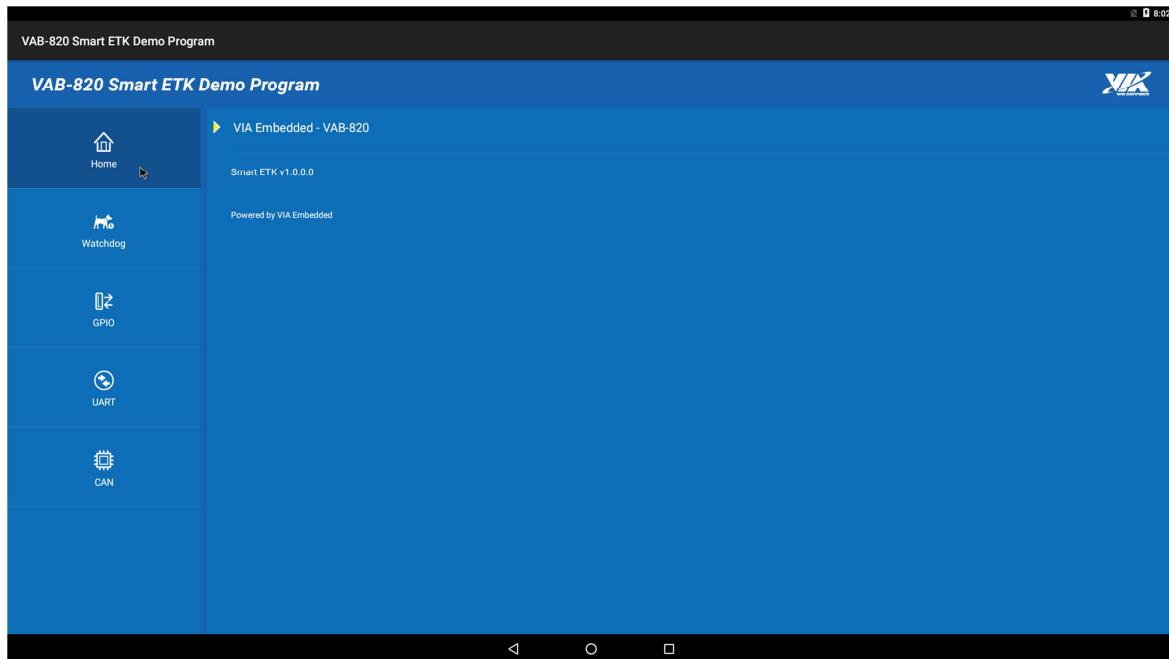
### 3.6.1. Installing Smart ETK

The first step is to copy the VAB-820\_Smart\_ETK\_Demo\_v1.0.apk onto a mass storage device such as a USB thumb drive. Next, from the Settings screen, click Security, and then switch on the “Unknown sources” as shown in the diagram below.



Finally, insert the USB thumb drive into the VAB-820 and double click on the VAB-820\_Smart\_ETK\_Demo\_v1.0.apk file to install.

When the installation process has completed, run the VAB-820\_Smart\_ETK\_Demo\_v1.0.apk and start to test the different functions with it.

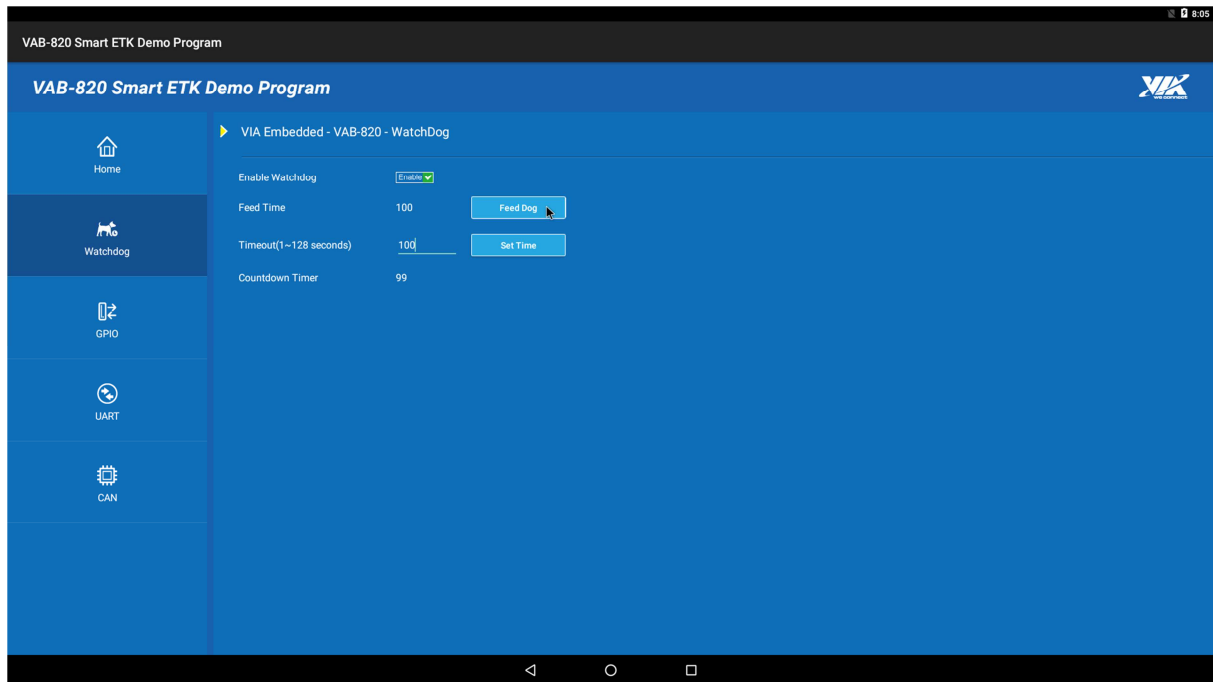


Smart ETK SDK sample screen



### 3.6.2. Testing Watchdog Timer Function

The Watchdog timer includes Enable/Disable, Set Timeout, Feed Dog, Feed time and Countdown Timer functions.



Smart ETK Watchdog timer diagram

First, please open the Smart ETK sample program then select Watchdog.

Next select Enable to active the Watchdog function.

Next, enter the time value (1~128 seconds) in the Timeout setting section.

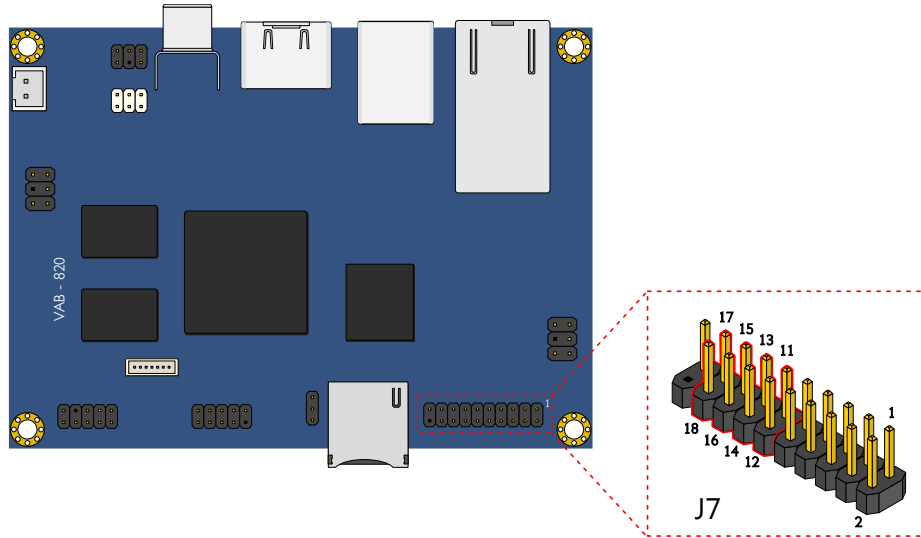
Click on the Feed Dog button to refresh the countdown time value back to the beginning.

The Feed time section shows the Timeout setting start value.

The Countdown time section shows the countdown time value.

### 3.6.3. Testing GPIO Function

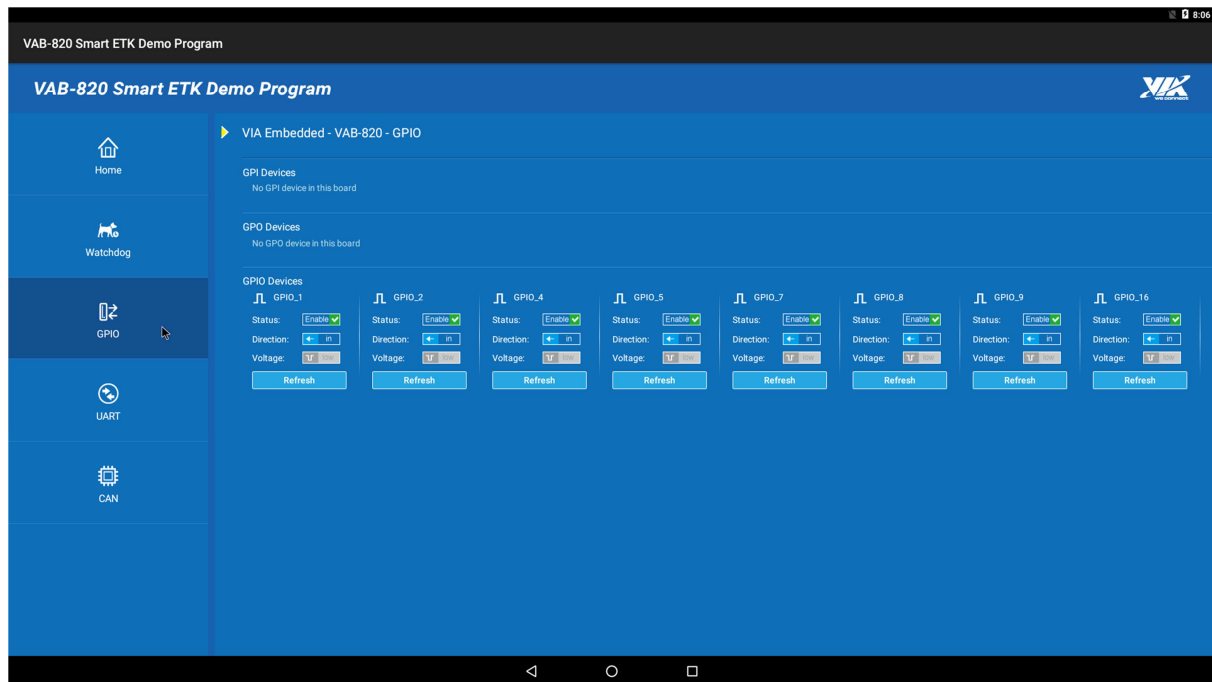
The GPIO pin header on the VAB-820 consists of 19 pins. Pins 11~18 are active. The following section explains setting up these pins for input/output communication.



GPIO pin header diagram

Pin	Signal	Pin	Signal
1	RESET_N	2	P_LED+
3	GND	4	P_LED-
5	12C3_SCL	6	W_LED+
7	12C3_SDA	8	W_LED-
9	5VIN	10	GND
11	GPIO_1	12	GPIO_7
13	GPIO_2	14	GPIO_8
15	GPIO_4	16	GPIO_9
17	GPIO_5	18	GPIO_16
19	GND	20	-

GPIO pin header pinout table



Smart ETK GPIO interface diagram

First, please open the Smart ETK sample program, then from the left side select GPIO to start testing. In the demo program, pins 11~18 have been set as programmable GPIO pins.

The toggles under each pin can be used to set the desired configuration.

Enable/Disable: Sets whether the pin function is enabled or disabled.

IN/OUT: Sets whether the pin is defined as input (in) or output (out).

If you have set a GPIO pin as an input (in), the Voltage value will show whether the input voltage signal is high or low.

Voltage low: the input signal is low for voltage level.

Voltage high: the input signal is high for voltage level.

If you have set the GPIO pin as an output (out), you can then set the output voltage to high or low with the Value setting.

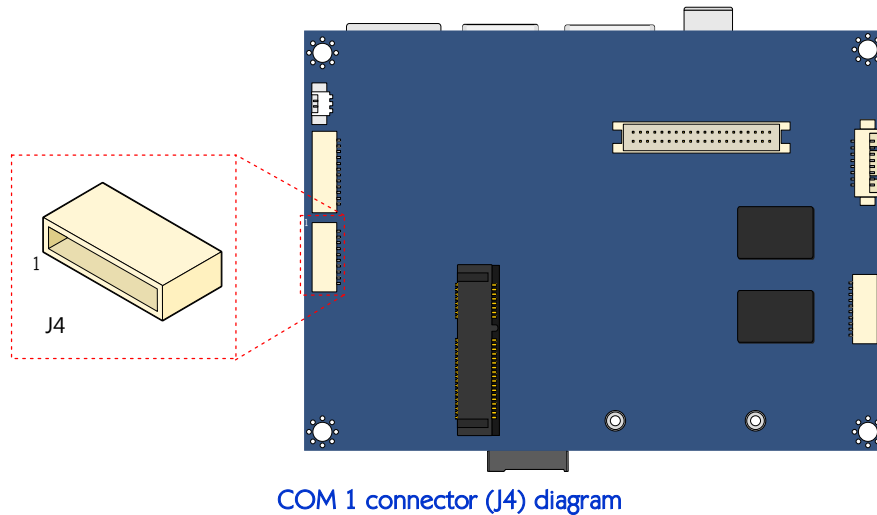
Voltage low: the output voltage signal is low.

Voltage high: the output voltage signal is high.

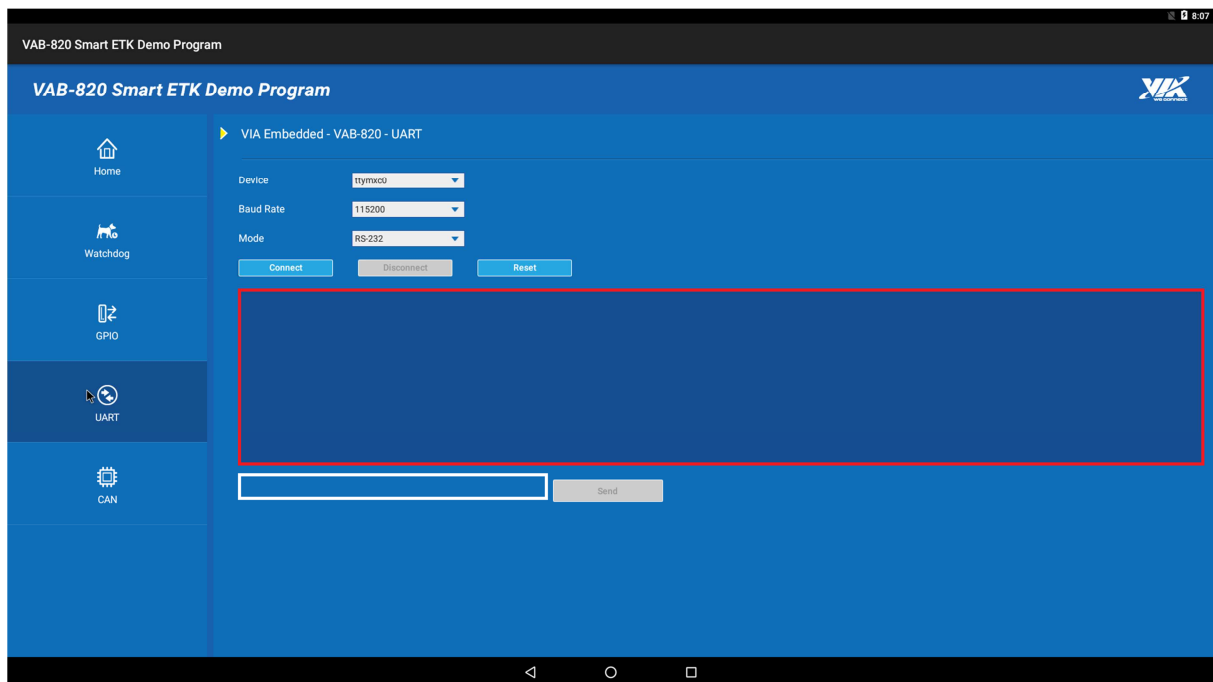
### 3.6.4. Testing UART Function

The VIA Smart ETK UART function supports TX/RX communication with other devices.

The first step is to connect the host machine to the COM 1 connector (J4) on the VAB-820. Next on the host machine start a serial communication program such as Putty, GtkTerm or Minicom with the same serial port setting using the appropriate serial device.



COM 1 connector (J4) diagram



Smart ETK UART diagram

First, please open the Smart ETK sample program, then from the left side of the Smart ETK sample page; select UART.

To begin, select "ttymxc0" from the device drop-down menu and a Baud rate of "115200" from the Baud Rate drop-down menu. The VAB-820 only supports mode "RS-232". Next, click on the Connect button to enable the UART function and start communication between the host machine and VAB-820 board.

When the host machine transfers data to the VAB-820, the data will be displayed inside the red frame.

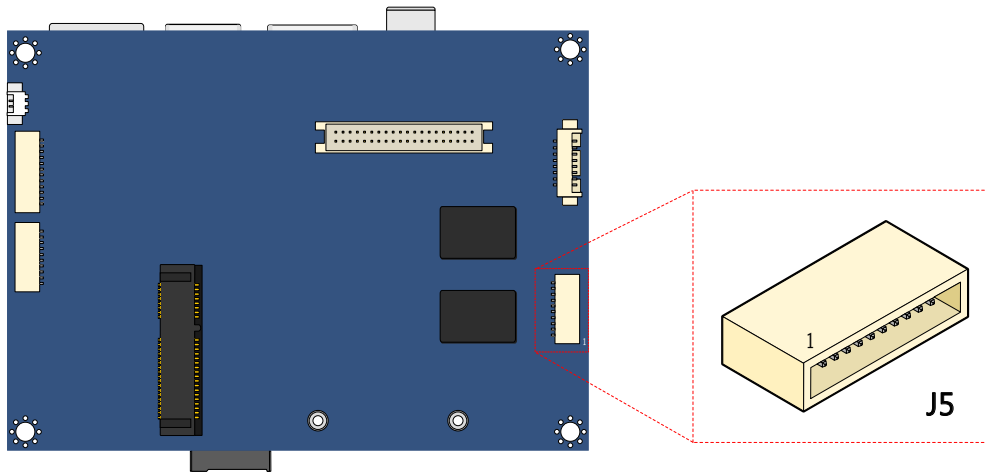
To send data from host machine to VAB-820, you need to type the data inside the white frame and click the Send button.

Click on the Disconnect button to disable this function.

Click on the Reset button to reset this function.

### 3.6.6. Testing FlexCAN Function

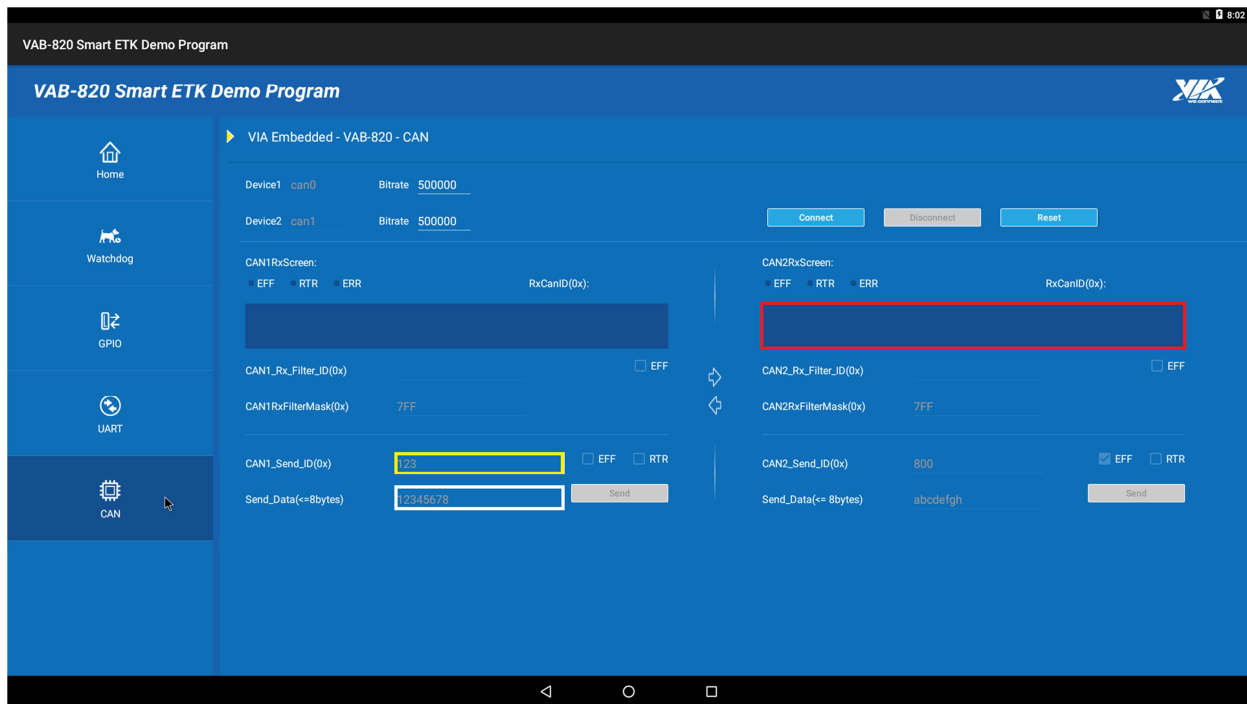
The CAN/COM 2 connector of the VAB-820 supports two CAN bus ports with FlexCAN protocol specification Version 2.0B.



CAN/COM 2 connector diagram

Pin	Signal
1	5VIN
2	COM2 RX
3	COM2 TX
4	NC
5	NC
6	GND
7	CAN RX2
8	CAN TX2
9	CAN TX1
10	CAN RX1

CAN/COM 2 connector pinout table



Smart ETK FlexCAN diagram

To begin, open the Smart ETK sample program and select CAN from the left side to access the Smart ETK CAN test interface.

The CAN ID frame structure is 32 bits. One frame includes: 1-bit EFF flag, 1-bit RTR flag, 1-bit ERR flag, an 18-bit extension ("identifier extension") and 11-bit identifier ("base identifier").

In order to use the identifier extension, you need to click "EFF".

If you select "RTR", the RTR-bit is transmitted as a dominant bit in the Data Frame and the Data Field will be empty in the Remote Field.

### 3.6.6.1. Basic CAN Bus Function Testing

In order to connect the CAN bus port for testing, you need to add an additional transceiver circuit. Please visit Texas Instruments website (<https://www.ti.com/>) to search Information on "TI SN65HVD1050 CAN Bus Transceiver".

After adding an additional transceiver circuit, the next step is to connect the corresponding signals between CAN1 and CAN2 as follows:

CAN1L to CAN2L and CAN1H to CAN2H

Next, in the Smart ETK program, set a Bit rate value between 5000 and 1000000 and then press "Connect" to establish a connection.

To test if the data can be transmitted, enter an ID in the CAN1\_Send\_ID block and data in the Send\_Data block and then click "Send".

When CAN1 transfers data to CAN2, the data will be displayed in the red block under the CAN2RxScreen section.

Click on the Reset button to reset this CAN bus function.

Click on the Disconnect button to disable this function.

### 3.6.6.2. Advanced CAN Bus Function Testing

For advanced testing, you will need to use the Filter\_ID and FilterMask functions.

The FilterMask is used to determine which bits in the identifier of the received frame are compared with the filter and the Filter\_ID is used to limit the data being sent and received through the CAN bus.

Note\* The Filter\_ID and FilterMask must be typed in hexadecimal values.

If a mask bit is set to zero, the corresponding ID bit will automatically be accepted, regardless of the value of the filter bit.

If a mask bit is set to one, the corresponding ID bit will be compared with the value of the filter bit.

If they match, it is accepted otherwise the frame is rejected.

Examples: There are four examples using hexadecimal values below.

#### Example 1

You wish to only accept frames with an ID of 00001567.

Set the Filter\_ID to 00001567 and the FilterMask to 1FFFFFFF.

When a frame arrives, its ID is compared with the filter and all bits must match; any frame that does not match ID 00001567 is rejected.

#### Example 2

You wish to only accept frames with IDs 00001560 thru to 0000156F.

Set the Filter\_ID to 00001560 and the FilterMask to 1FFFFFF0.

When a frame arrives, its ID is compared with the filter and all bits except bits 0 to 3 must match; any other frame is rejected.



**Example 3**

You wish to only accept frames with IDs of 00001560 thru to 00001567.

Set the Filter\_ID to 00001560 and the FilterMask to 1FFFFFF8.

When a frame arrives its ID is compared with the filter and all bits except bits 0 to 2 must match; any other frame is rejected.

**Example 4**

You wish to accept any frame.

Set the Filter\_ID to 0 and FilterMask to 0.

All frames are accepted.

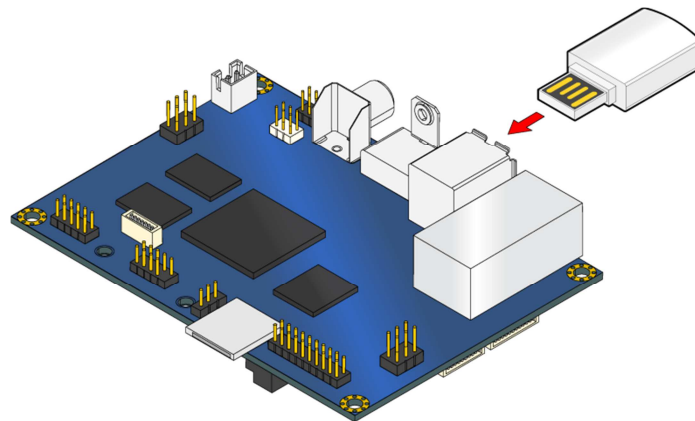
## 4. Accessories

This section explains how to install and configure the various EMIO wireless modules available for the VAB-820 board.

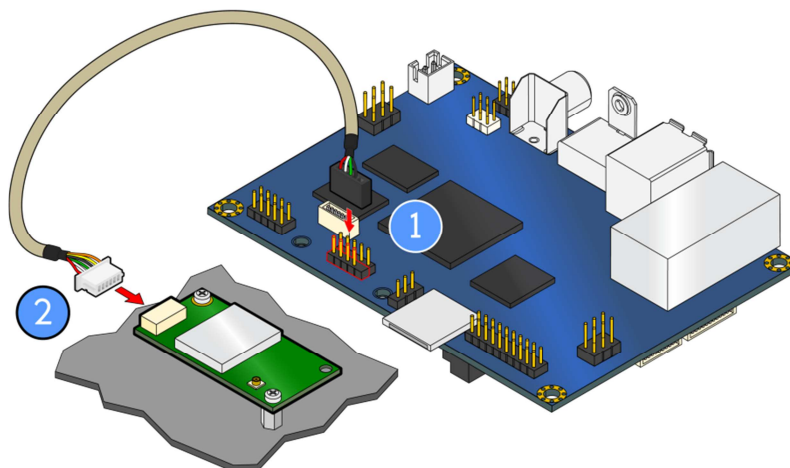
### 4.1. Configuring the VNT9271 USB Wi-Fi Dongle / EMIO-1533 USB Wi-Fi Module

The VNT9271 USB Wi-Fi dongle and EMIO-1533 USB Wi-Fi module support Wi-Fi functionality through USB port or onboard USB pin header connection respectively.

The first step is to insert the VNT9271 USB Wi-Fi dongle into a USB port or connect the EMIO-1533 module to the onboard USB pin header (J8) using the USB cable (P/N: 99G3-190042). After installing the EMIO-1533 module, the antenna must be installed as well. Next, make sure to unplug any LAN cables or other Wi-Fi/3G modules you have installed. Finally, power on the VAB-820.

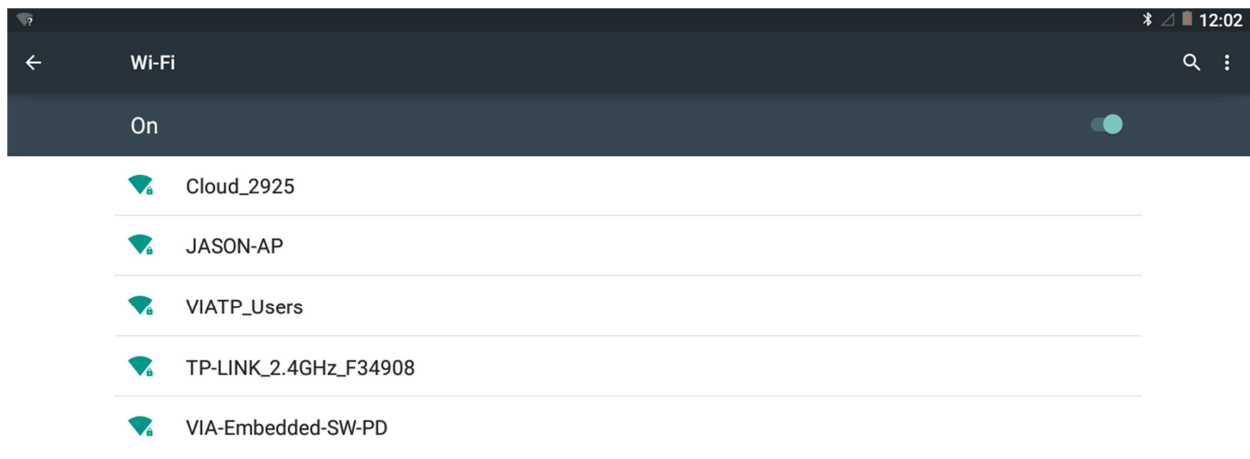


Inserting the VNT9271 USB Wi-Fi dongle



Connecting the EMIO-1533 module

To enable the Wi-Fi, go to Settings -> Wi-Fi-> On.



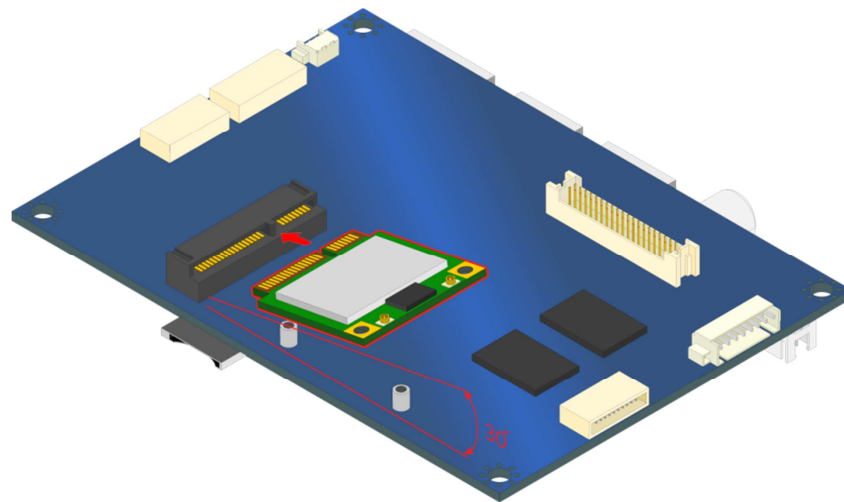
A list of Wi-Fi devices will appear on the screen, select the appropriate device to complete the Wi-Fi connection.

When the connection is created, connect to the internet through your web browser.

## 4.2. Configuring the EMIO-1541 miniPCle Wi-Fi Module

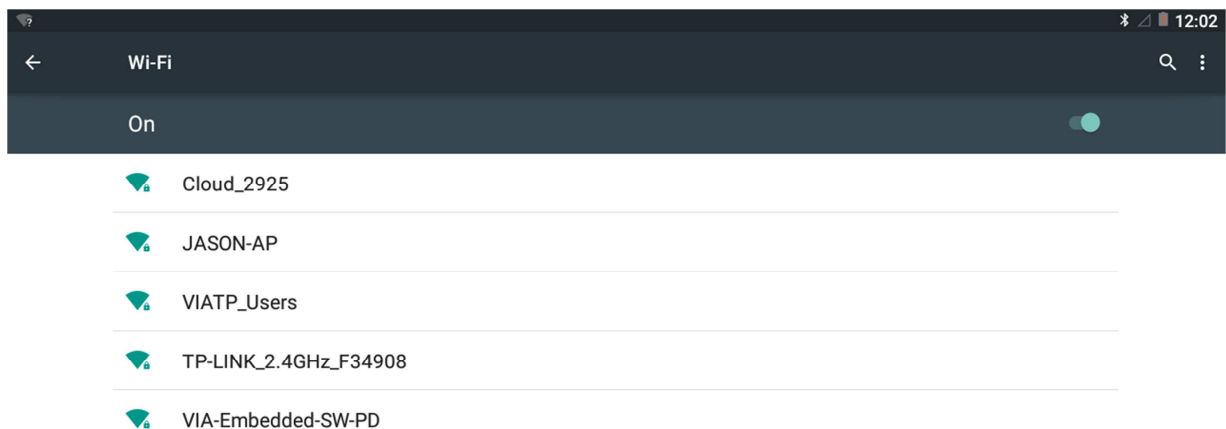
The EMIO-1541 miniPCle Wi-Fi module supports Wi-Fi function.

The first step is to insert the EMIO-1541 module into the miniPCle slot. After installing the module connect the provided antenna to the module. Next, make sure to unplug any LAN cables or USB Wi-Fi dongles you have installed. Finally, power on the VAB-820.



Inserting the EMIO-1541 module

To enable the Wi-Fi, go to Settings -> Wi-Fi-> On.



A list of Wi-Fi devices will appear on the screen, select the appropriate device to complete the Wi-Fi connection.

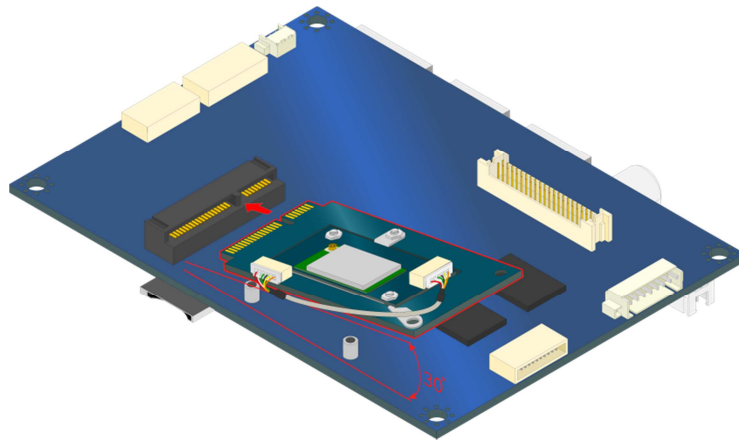
After the connection is created, connect to the internet through your web browser.

### 4.3. Configuring the EMIO-2531 miniPCle / EMIO-5531 USB Wi-Fi & Bluetooth Module

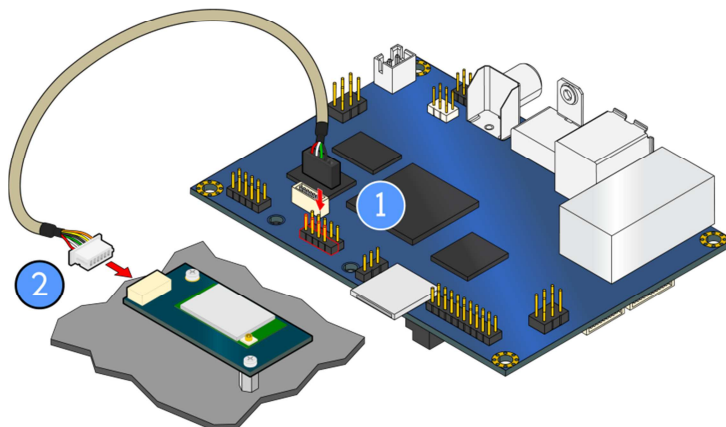
The EMIO-2531 miniPCle Wi-Fi & Bluetooth module and EMIO-5531 USB Wi-Fi & Bluetooth module support Wi-Fi and Bluetooth functions.

#### 4.3.1. Connecting to the Internet

The first step is to insert the EMIO-2531 module into the miniPCle slot or connect the EMIO-5531 module to the onboard USB pin header (J8) using the USB cable (P/N: 99G3-190042). After installing either module connect the provided antenna to the module. Next, make sure to unplug any LAN cables or other Wi-Fi/3G modules you have installed. Finally, power on the VAB-820.

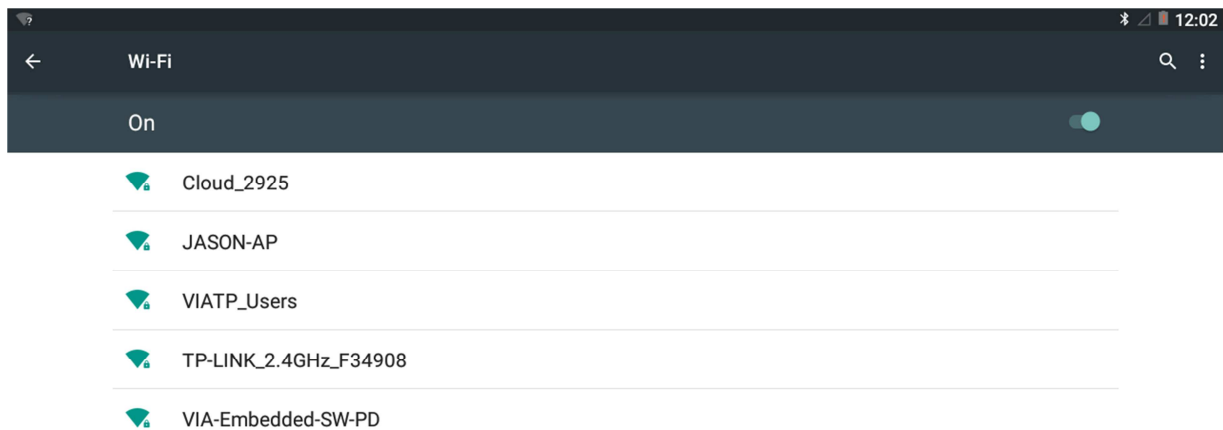


Inserting the EMIO-2531 module



Connecting the EMIO-5531 module

To enable the Wi-Fi, go to Settings -> Wi-Fi-> On.



A list of Wi-Fi devices will appear on the screen, select the appropriate device to complete the Wi-Fi connection.

When the connection is created, connect to the internet through your web browser.

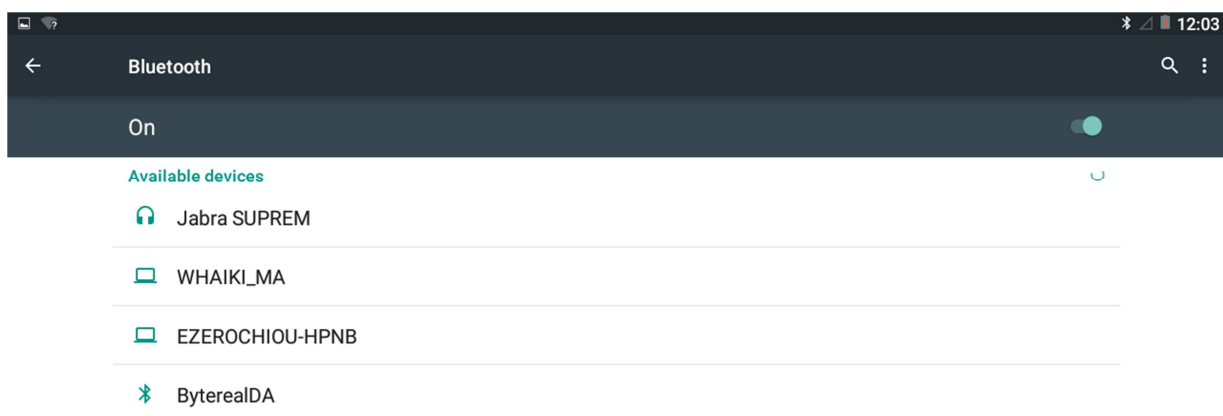
## 4.3.2. Enabling Bluetooth

The following sections show how to enable the Bluetooth Advanced Audio Distribution Profile (A2DP) to allow audio playback through a connected Bluetooth device as well as how to configure the Bluetooth Serial Port Profile (SPP).

### 4.3.2.1. Setting Up Bluetooth A2DP Profile

First, put the accessory you want to use into discovery mode. The exact way to do this depends on the accessory. If you have a headset, you may need to hold a button down on the headset for several seconds until a light starts flashing. It will only stay discoverable for a few minutes.

If you are not sure how to put your accessory into discovery mode, please refer to its manual, check the manufacturer's website, or perform a web search for instructions. To enable the Bluetooth A2DP function, go to Settings -> Bluetooth and set the switch to On to enable the Bluetooth function.



A list of local devices will appear on the screen, select the appropriate device to complete the Bluetooth pairing.

#### 4.3.2.2. Setting Up Bluetooth SPP Profile

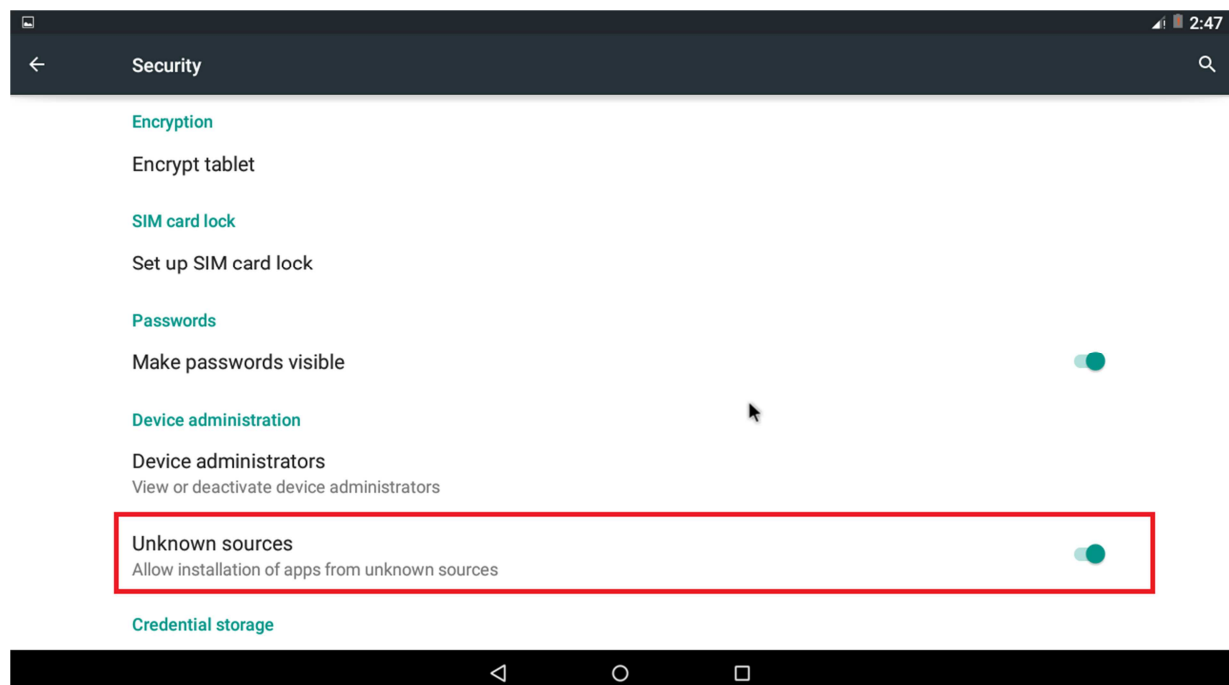
The first step is to copy the **BluetoothSPPTest.apk** onto a mass storage device such as USB thumb drive. Next, from the Settings screen, click Security -> Unknown sources to allow installation of non-Market apps.

The VAB-820 implements the Bluetooth Serial Port Profile allowing serial port communication between two Android devices.

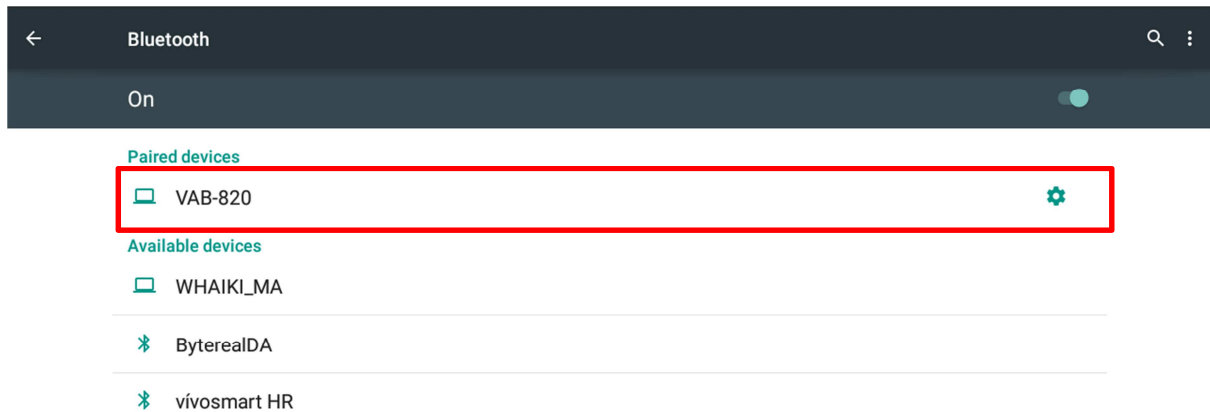
Included in the VAB-820 Tools folder is the BluetoothSPPTest.apk which is a simple communication application which utilizes the Bluetooth SPP Profile to transmit and receive data between two paired Android devices.

The following example will demonstrate how to use the BluetoothSPPTest.apk to communicate over the Bluetooth SPP Profile between two VAB-820 boards.

First, the **BluetoothSPPTest.apk** must be installed onto each VAB-820 board. From the Settings screen, click Security -> and then switch on the "Unknown sources" and allow the installation of non-Market apps. Next, copy the **BluetoothSPPTest.apk** onto a mass storage device, such as USB thumb drive, and install the **BluetoothSPPTest.apk** onto both VAB-820 boards.



After the installation process has completed, go to Settings -> Bluetooth -> On to enable the Bluetooth function on both VAB-820 systems.



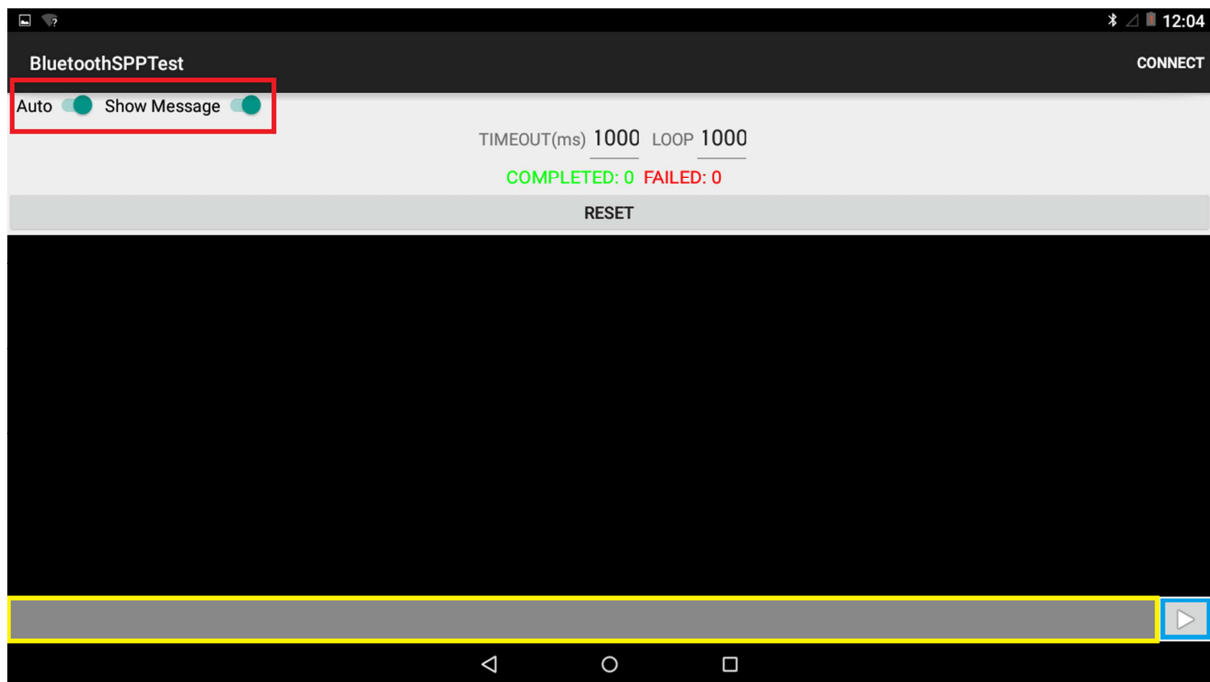
A list of local devices will then appear on each screen. From either screen, select the VAB-820 system from the list to complete the pairing process as seen in the figure below.

After the devices have paired, open the **BluetoothSPPTest.apk** on both VAB-820 systems and configure the settings as follows in both apps.

“Auto” – enabled

“Show Message” – enabled

Select **CONNECT** from either VAB-820 boards to create the connection between the two. Both VAB-820 boards can communicate over the Bluetooth SPP Protocol.



BluetoothSPPTest diagram

Type the data inside the yellow frame and click the blue frame to send the data through either VAB-820 boards, this data will be shown on the other VAB-820 board.

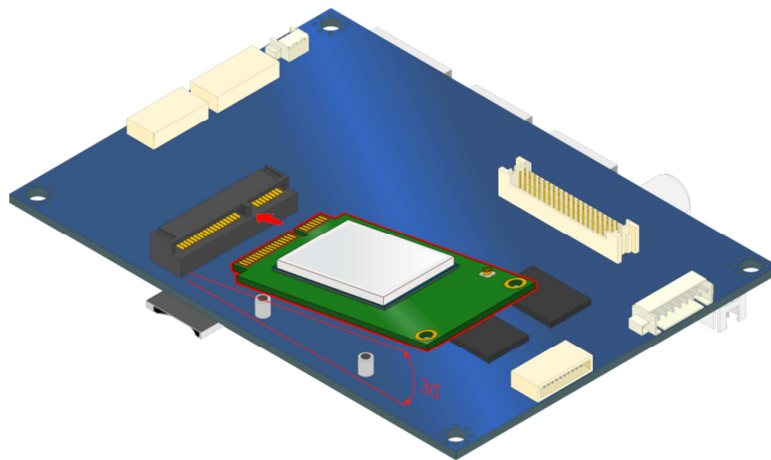


## 4.4. Configuring the EMIO-2550 miniPCle Mobile Broadband Module

The EMIO-2550 miniPCle Mobile Broadband module supports 3G and GPS functions.

### 4.4.1. Connecting to the Internet.

The first step is to insert an active SIM card into the EMIO-2550 module, and then insert the EMIO-2550 module into the miniPCle slot. After installing the module connect the provided antenna to the module. Next, make sure to unplug any LAN cables or USB Wi-Fi dongles you have installed. Finally, power on the VAB-820.



Inserting the EMIO-2550 module

To check that the system has correctly detected the EMIO-2550 module, use the following command:

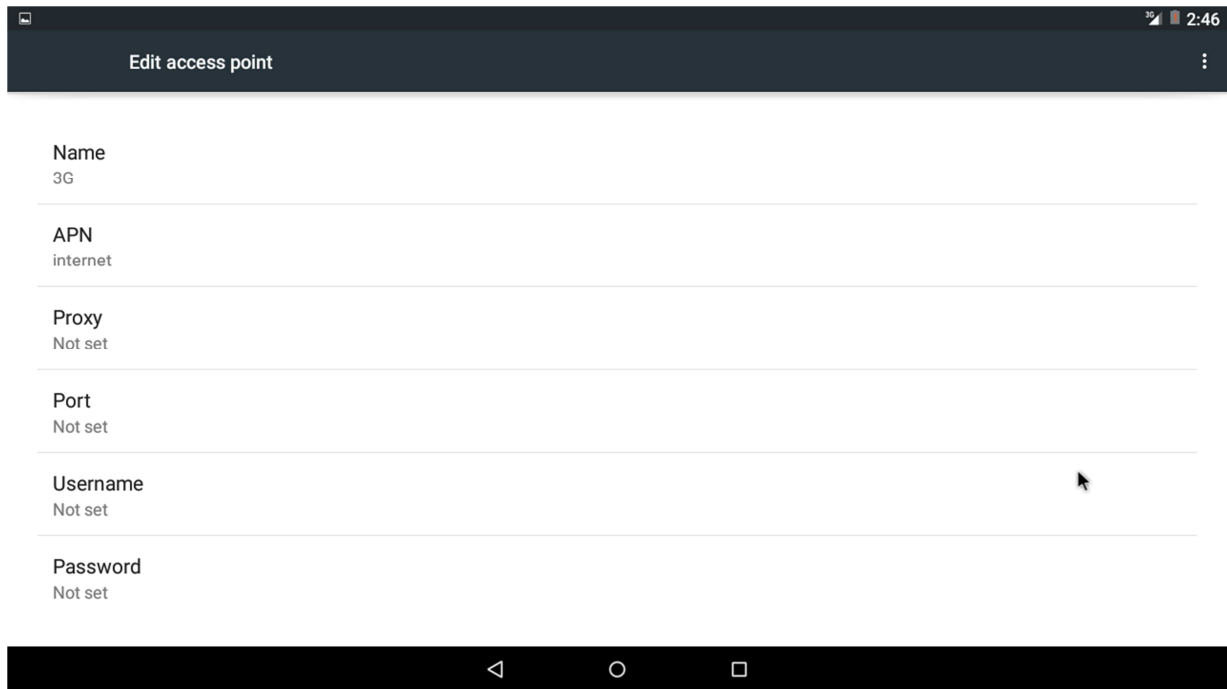
```
root@vab820_6dq:/ # busybox ifconfig
```

Make sure the printout message includes “ppp0 Link encap: Point-to-Point Protocol”.

To enable the 3G, go to Settings->Wireless & networks-> More -> Cellular network -> Access Point Names. Next, click the plus button to add your APNs setting.



Fill in the required fields for APNs setting. If you are unsure of what the required fields and value are, check with your Mobile Broadband provider.



**Edit access point**

Name  
3G

APN  
internet

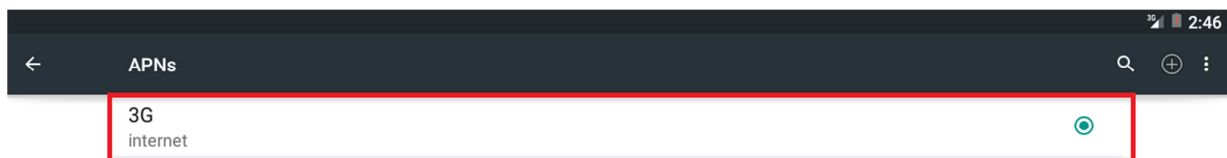
Proxy  
Not set

Port  
Not set

Username  
Not set

Password  
Not set

When the APNs setting is completed, click your APNs to enable the 3G network. Next, open the browser to connect to the Internet.

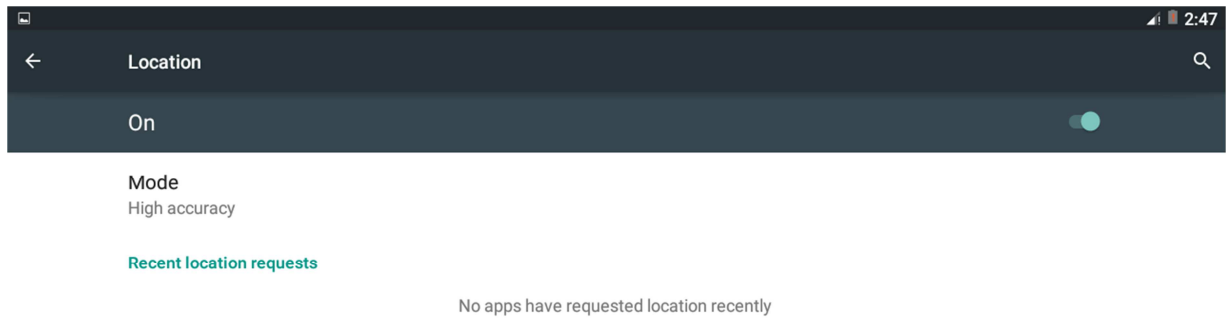


**APNs**

3G  
internet

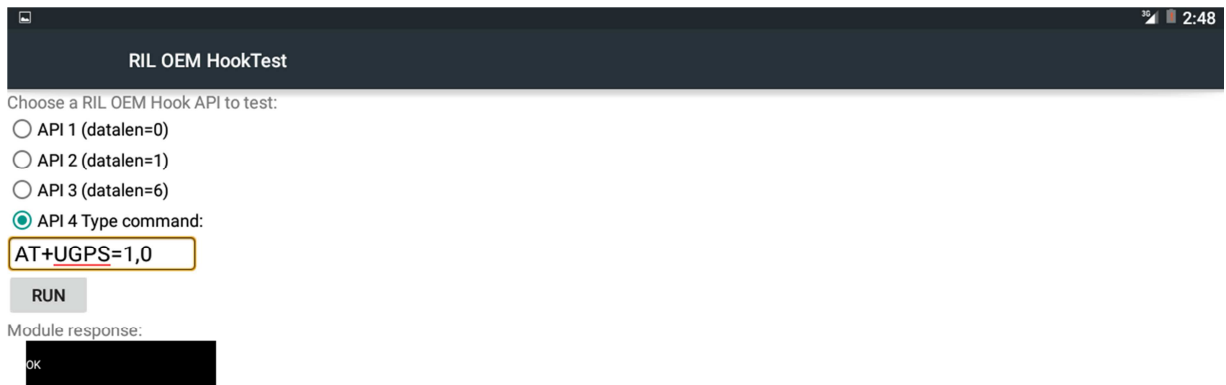
## 4.4.2. Enabling GPS

To enable the GPS, go to Settings->Location ->On to enable GPS function.



Next, go to Settings-> Wireless & networks-> More -> RIL OEM Hook Test -> API 4 Type command. Full in "AT+UGPS=1,0" and click RUN.

Wait for the "OK" message and open the GPS program.





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